Ideal Simplicial Volume

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Relative simplicial volume & Examples

Definition. Given a chain $c = \sum_{j=0}^{k} a_j \cdot \sigma_j \in C_*(M, \partial M; \mathbb{R})$, we define the ℓ^1 -norm of c as $|c|_1 := \sum_{j=0}^{k} |a_j|$. Given a connected, compact and oriented manifold with boundary M, we define the **relative simplicial volume (RSV)** of M, ||M||, to be $||M|| = \inf\{|c|_1 \mid c \in C_n(M, \partial M; \mathbb{R}) \text{ such that } [c] = [M, \partial M]\} \in \mathbb{R}_{\geq 0}$, where $[M, \partial M] \in H_n(M, \partial M; \mathbb{R})$ is the relative fundamental class of M.

Theorem ([1]). If M is either a handlebody of genus $g \ge 2$ or it is the product of a surface with an interval, then its relative simplicial volume ||M|| is proportional to $||\partial M||$.

Theorem ([4]). If M is the natural compactification of a complete finite-volume hyperbolic n-manifold, then $||M|| = Vol(M)/v_n$.

MARKED SPACES & IDEAL TRIANGULATIONS

Definition. A marked space is a topological pair (X, B) such that B is a closed and discrete subset of X in which each point $b \in B$ has a closed neighbourhood in X homeomorphic to a topological cone.

Definition. Given a manifold with boundary M, we define the **marked space associated to** M, $(X, B)_M$, as follows: X is the topological quotient obtained from M by collapsing separately each connected component of ∂M , while B is the finite subset of X corresponding to the connected components of ∂M .

Definition. An ideal triangulation of M is the realization of $(X, B)_M$ as a Δ -complex whose set of

EXAMPLE



MARKED HOMOLOGY

Definition. Given a marked space (X, B), a singular simplex $\sigma: \Delta^n \to X$ is said to be **admissible** if $\sigma^{-1}(B)$ is a (possibly empty) subcomplex of Δ^n . The set of admissible simplices in X defines a subcomplex $\widehat{C}^{\mathcal{M}}_*(X, B; \mathbb{R})$ of the singular complex $C_*(X; \mathbb{R})$ which contains $C_*(B; \mathbb{R})$. We define the **marked chain complex** of (X, B) to be $C^{\mathcal{M}}_*(X, B; \mathbb{R}) = \widehat{C}^{\mathcal{M}}_*(X, B; \mathbb{R})/C_*(B; \mathbb{R})$. The **marked homology** of (X, B), $H^{\mathcal{M}}(X, B; \mathbb{R})$, is the homology of the marked chain complex $(C^{\mathcal{M}}_*(X, B; \mathbb{R}), \partial_*)$.

Theorem 1 ([2]). *There exists an isomorphism* $\Psi_n : H_n(M, \partial M; \mathbb{R}) \xrightarrow{\cong} H_n^{\mathcal{M}}(X, B; \mathbb{R}).$

IDEAL SIMPLICIAL VOLUME

Definition. Let M be a connected, compact, oriented n-manifold with boundary. We define the **ideal simplicial volume (ISV)** of M, $||M||_{\mathcal{I}}$ to be $||M||_{\mathcal{I}} = \inf\{|c|_1 | c \in C_n^{\mathcal{M}}(M, \partial M; \mathbb{R}) \text{ such that } [c] = [M, \partial M]^{\mathcal{M}} \} \in \mathbb{R}_{\geq 0}$, where $[M, \partial M]^{\mathcal{M}} \in H_n^{\mathcal{M}}(M, \partial M; \mathbb{R})$ is the marked fundamental class of M, that is $[M, \partial M]^{\mathcal{M}} = \Psi_n([M, \partial M])$.

FUNDAMENTAL PROPERTIES

Theorem 2 ([2]). The minimal number of simplices in an ideal triangulation of a compact manifold M, c(M), provides an upper bound of the ideal simplicial volume:

 $||M||_{\mathcal{I}} \le c(M).$

Theorem 3 ([2]). Let $f: (M, \partial M) \rightarrow (N, \partial N)$ be a map of pairs between compact connected oriented manifolds of the same dimension. Then, the following holds:

 $||M||_{\mathcal{I}} \ge |deg(f)|||N||_{\mathcal{I}}.$

In particular, the ideal simplicial volume is a **homotopy invariant** of manifolds with boundary (where homotopies are understood to be homotopies of pairs).

ISV VERSUS RSV

Theorem 4 ([2]). There exists a positive constant K_n only depending on the dimension n of M such that the following holds:

 $\|M\|_{\mathcal{I}} \le \|M\| \le K_n \|M\|_{\mathcal{I}}.$

In particular, $||M||_{\mathcal{I}} = 0$ if and only if ||M|| = 0.

Theorem 5 ([2]). Let *M* be an *n*-dimensional compact manifold such that each of its boundary components has **amenable** fundamental group. Then,

 $\|M\|_{\mathcal{I}} = \|M\|.$

In particular, when M is the compactification of a complete finite-volume

A HYPERBOLIC TRUNCATED TETRAHEDRON



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hyperbolic n-manifold, then $||M||_{\mathcal{I}} = \frac{Vol(M)}{v_n}$.

NEW COMPUTATIONS

Theorem 6 ([3]). Let $\ell \leq \cosh^{-1}((3 + \sqrt{3})/4)$. Then, regular hyperbolic truncated tetrahedra of edge length ℓ maximize the volume among hyperbolic truncated tetrahedra whose edge lengths are all not smaller than ℓ .

The previous technical result is a fundamental step in the computation of the ISV of an infinite family of hyperbolic 3-manifolds with geodesic boundary, for which the exact value of the RSV is not known:

Theorem 7 ([2]). For any hyperbolic 3-manifolds M with connected geodesic boundary of genus $g \ge 2$, we have

 $\|M\|_{\mathcal{I}} \ge \mathsf{g}.$

Moreover, the equality holds if and only if M admits an ideal triangulation with **g** ideal simplices.